

# Hausdorff dimension and dendritic limit sets.

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## Abstract.

Let  $\Gamma$  be a singly degenerate closed surface group acting properly discontinuously on hyperbolic 3-space,  $\mathbf{H}^3$ , such that  $\mathbf{H}^3/\Gamma$  has positive injectivity radius. It is known that the limit set is a dendrite of Hausdorff dimension 2. We show that the cut-point set of the limit set has Hausdorff dimension strictly less than 2.

## 0. Introduction.

Let  $\Sigma$  be a closed orientable surface with  $\text{genus}(\Sigma) \geq 2$ , and let  $\Gamma = \pi_1(\Sigma)$ . Suppose that  $\Gamma$  acts properly discontinuously on hyperbolic 3-space  $\mathbf{H}^3$ . Since  $\Gamma$  is torsion-free, the quotient  $M = \mathbf{H}^3/\Gamma$  is a hyperbolic 3-manifold, with  $\pi_1(M) \equiv \Gamma$ . Its limit set,  $\Lambda\Gamma$ , is a subcontinuum of the 2-sphere  $S^2 \equiv \partial\mathbf{H}^3$ . Of particular interest is the case where  $M$  is “singly degenerate” so that  $\partial\mathbf{H}^3 \setminus \Lambda\Gamma$  is a topological disc. If, in addition,  $M$  has positive injectivity radius,  $\text{inj}(M) > 0$ , then  $\Lambda\Gamma$  is known to be a dendrite [Min1,Min2]. Moreover, it is shown in [S] that its Hausdorff dimension equals 2.

In contrast, we show:

**Theorem 0 :** *The cut-point set of the dendrite  $\Lambda\Gamma$  has Hausdorff dimension at most  $2 - \epsilon$ , where  $\epsilon > 0$  depends only on  $\text{inj}(M)$  and  $\text{genus}(\Sigma)$ .*

It clearly follows that the set of extreme (i.e. non-cut) points of  $\Lambda\Gamma$  has Hausdorff dimension 2. (Since every conical limit point is an extreme point, this observation also follows from [BiJ].) In principle, a lower bound on  $\epsilon$  is computable in terms of  $\text{inj}(M)$  and  $\text{genus}(\Sigma)$ , but we shall not make any explicit estimate here. Theorem 0 will follow easily from a stronger statement, namely Theorem 2.1.

This result was inspired by a recent result of Miyachi [Miy] which shows that any pair of points in  $\Lambda\Gamma$  are connected by a quasi-arc in  $\Lambda\Gamma$ . A quasi-arc has Hausdorff dimension strictly less than 2, and  $\Lambda\Gamma$  is a countable union of such arcs. The additional ingredient is thus a uniform bound on these Hausdorff dimensions.

As in [Miy], the essential point is to show that any arc in  $\Lambda\Gamma$  lies in the boundary of a half-plane quasi-isometrically embedded in  $\mathbf{H}^3$ . Instead of using the full force of the result of [Min2], we proceed directly from the singly degenerate assumption, using ideas of Mitra [Mit], as laid out explicitly in [Bow2].

## 1. Quasidendrites.

First we recall some basic facts about dendrites, and introduce the notion of a “quasidendrite” — by analogy with the standard notions of “quasicircle” and “quasi-arc”. (Note that the prefix “quasi-” is used in two different senses in this paper: here from the association with quasiconformal maps, and elsewhere from the association with quasi-isometries.)

There are numerous equivalent definitions of a dendrite. For example, a dendrite,  $D$ , is a locally connected metrisable continuum in which any pair of points,  $x, y \in D$ , are connected by a unique arc,  $I[x, y] \subseteq D$ . (Here an “arc” is a subset homeomorphic to a closed real interval.) We write  $I(x, y) = I[x, y] \setminus \{x, y\}$ . One shows that a point  $z \in D$  is a cut point if and only there exist  $x, y \in D$  such that  $z \in I(x, y)$ . We write  $\text{cut}(D) \subseteq D$  for the set of cut points. A point of  $D \setminus \text{cut}(D)$  is called an *extreme* point.

Since  $D$  is metrisable, it contains a countable dense subset  $P \subseteq D$ . One can easily show that  $\text{cut}(D) \subseteq \bigcup_{x, y \in P} I[x, y]$ . In particular,  $\text{cut}(D)$  is a countable union of open subarcs.

Given four points,  $x, y, z, w$  in the Riemann sphere,  $\mathbf{C} \cup \{\infty\}$ , we define their *crossratio*,  $[x, y : z, w]$ , as  $\frac{(w-z)(y-x)}{(w-y)(z-x)}$ . Thus,  $[x, y : z, \infty] = \frac{y-x}{z-x}$ .

First recall the notion of a  $K$ -quasicircle (cf. [LV]), for  $K \geq 1$ . This can be defined as a simple closed curve,  $\alpha \subseteq \mathbf{C} \cup \{\infty\}$ , such that whenever  $\{x, z\} \subseteq \alpha$  is linked with  $\{y, w\} \subseteq \alpha$ , we have  $|[x, y : z, w]| \leq K$ . Mapping  $w$  to  $\infty$  by a Möbius transformation, this means that if  $\beta \subseteq \alpha \setminus \{\infty\}$  is any compact subarc with endpoints  $\partial\beta$ , then  $\text{diam}(\beta) \leq K \text{diam}(\partial\beta)$ , where  $\text{diam}$  denotes euclidean diameter. From this, one can deduce that the Hausdorff dimension of  $\alpha \setminus \{\infty\}$  is at most  $2 - \epsilon$ , where  $\epsilon > 0$  depends only on  $K$ . Since Möbius transformations are smooth, the same applies to  $\alpha$  with respect to either the spherical or euclidean metrics.

We can similarly define a *quasi-arc*,  $\gamma$ , where  $x, y, z, w$  are assumed to occur in this order along  $\gamma$ . The same discussion applies. More generally:

**Definition :** Let  $D \subseteq \mathbf{C} \cup \{\infty\}$  be a dendrite embedded in the Riemann sphere. We say that  $D$  is a  $K$ -quasidendrite if, given any distinct  $x, y, z, w \in D$  such that  $y$  separates  $x$  from  $z$  and  $z$  separates  $y$  from  $w$ , then  $|[x, y : z, w]| \leq K$ .

Note that the condition on  $x, y, z, w$  is equivalent to asserting that  $y, z \in I(x, w)$  and  $x, y, z, w$  occur in this order along  $I[x, w]$ . In other words, we are saying that each subarc of  $D$  is a  $K$ -quasi-arc. Since the cut-point set,  $\text{cut}(D)$ , lies on a countable union of such quasi-arcs, we conclude:

**Lemma 1.1 :** *Given  $K \geq 1$ , there is some  $\epsilon > 0$  such that if  $D \subseteq \mathbf{C} \cup \{\infty\}$  is a  $K$ -quasidendrite, then the Hausdorff dimension of  $\text{cut}(D)$  is at most  $2 - \epsilon$ .*

We note that to verify that a dendrite  $D$  is a quasidendrite, it is enough, by continuity, to consider  $x, y, z, w \in \text{cut}(D)$ .

We also note the following geometric interpretation of the crossratio bound, which is what we will verify in practice. First, identify  $\mathbf{C} \cup \{\infty\}$  with boundary,  $\partial\mathbf{H}^3$ , of hyperbolic

3-space,  $\mathbf{H}^3$ . Given  $x, y \in \mathbf{H}^3 \cup \partial\mathbf{H}^3$ , we denote by  $[x, y]$  the hyperbolic geodesic from  $x$  to  $y$ . We write  $d$  for the hyperbolic metric on  $\mathbf{H}^3$ . If  $x, y, z, w \in \partial\mathbf{H}^3$ , then  $d([x, z], [y, w]) = |\log|\mu||$ , where  $\mu \in \mathbf{C} \setminus \{0\}$  satisfies  $4[x, y : z, w] = \mu + \mu^{-1} - 2$ . In particular, we see that an upper bound on  $[[x, y : z, w]]$  is equivalent to an upper bound on  $d([x, z], [y, w])$ .

## 2. Kleinian groups.

We recall some basic facts about kleinian groups and give a more precise formulation of our main theorem.

By a *kleinian group*, we shall mean a group  $\Gamma$  acting freely and properly discontinuously on hyperbolic 3-space,  $\mathbf{H}^3$ . We write  $\Lambda\Gamma \subseteq \partial\mathbf{H}^3$  for its limit set, and  $M = M(\Gamma) = \mathbf{H}^3/\Gamma$  for the quotient 3-manifold. The *injectivity radius*,  $\text{inj}(M)$ , of  $M$  is twice the infimum of lengths of essential closed curves in  $M$ .

An important class of groups arises when  $\Gamma = \pi_1(\Sigma)$  is the fundamental group of a closed orientable surface,  $\Sigma$ , with  $\text{genus}(\Sigma) \geq 2$ . (The non-orientable case is essentially the same, or can be dealt with passing to a double cover.) In this case, Bonahon [Bon] shows that  $M$  is geometrically tame (in particular, homeomorphic to  $\Sigma \times \mathbf{R}$ ). If there are no parabolics, then each end of  $M$  is either geometrically finite or simply degenerate. Depending on whether  $M$  has 2, 0 or 1 simply degenerate ends, the limit set,  $\Lambda\Gamma$ , will be respectively, all of  $\partial\mathbf{H}^3$ , a quasicircle, or a continuum,  $D$ , with  $\partial\mathbf{H}^3 \setminus D$  a disc. It is the last, “singly degenerate”, case that interests us here ( $\Gamma$  is sometimes called a “Bers group”). It is conjectured that  $D$  is always a dendrite, and this is known to be the case if  $\text{inj}(M) > 0$  [Min2]. Moreover, under the same hypotheses, Sullivan [S] showed that the Hausdorff dimension of  $D$  equals 2. (For a much more general statement, see [BiJ].) In contrast, Miyachi [Miy] showed that every subarc of  $D$  is a quasi-arc. However, his argument does not give a uniform constant. We use a slightly different approach to give our main result:

**Theorem 2.1 :** *Let  $\Sigma$  be a closed orientable surface with  $\text{genus}(\Sigma) \geq 2$ . Let  $\Gamma = \pi_1(\Sigma)$  act on  $\mathbf{H}^3$  as a singly degenerate kleinian group with  $\text{inj}(\mathbf{H}^3/\Gamma) > 0$ . Then the limit set,  $\Lambda\Gamma$ , is a  $K$ -quasidendrite, where  $K$  depends only on  $\text{inj}(\mathbf{H}^3/\Gamma)$  and  $\text{genus}(\Sigma)$ .*

Again, the dependence of  $K$  on  $\text{inj}(M)$  and  $\text{genus}(\Sigma)$  is, in principle, computable.

Putting Theorem 2.1 together with Lemma 1.1, we immediately deduce Theorem 0.

## 3. Riemannian half-planes.

As in [Miy] we shall prove the main result by constructing quasi-isometric maps of half-planes into  $\mathbf{H}^3$ . We begin with a general discussion of half-planes.

Let  $H$  be a complete path-metric space homeomorphic to  $\mathbf{R} \times [0, \infty)$ . (We can assume  $H$  to be riemannian if we want.) We suppose  $H$  to be hyperbolic in the sense of Gromov [Gr,GhH]. We write  $\partial H$  for its Gromov boundary, so that  $H \cup \partial H$  is compact. To avoid

any confusion, we shall refer to  $\mathbf{R} \times \{0\}$  as the *frontier* of  $H$ , and denote it by  $\text{fr}(H)$ . We shall assume that the closure of  $\text{fr}(H)$  in  $H \cup \partial H$  is homeomorphic to a closed real interval with endpoints  $\text{end}(H) = \{a, b\} \subseteq \partial H$ . Since  $H$  is one-ended, we know that  $\partial H$  is connected (see, for example, [GhH]). In fact:

**Lemma 3.1 :**  *$\partial H$  is homeomorphic to a closed interval with endpoints  $\text{end}(H)$ .*

**Proof :** Since  $\partial H$  is metrisable, it's enough to show that each point,  $c$ , of  $\partial H \setminus \text{end}(H)$  separates  $a$  from  $b$ . To this end, let  $\gamma$  be a geodesic ray with basepoint in  $\text{fr}(H)$  and converging on  $c$ . By cutting  $\gamma$  off at its last intersection point with  $\text{fr}(H)$ , we can assume that  $\gamma$  meets  $\text{fr}(H)$  in a single point. This point cuts  $\text{fr}(H)$  into two rays,  $\alpha$  and  $\beta$ , converging on  $a$  and  $b$  respectively.

Now  $\gamma$  cuts  $H$  into two half-planes,  $H_a$  and  $H_b$ , so that  $\text{fr}(H_a) = \alpha \cup \gamma$  and  $\text{fr}(H_b) = \beta \cup \gamma$ . Now  $H_a$  and  $H_b$  are convex and hence intrinsically Gromov hyperbolic. We have  $\partial H_a \cap \partial H_b = \{c\}$ ,  $\partial H_a \cup \partial H_b = \partial H$ , and  $a \in \partial H_a$  and  $b \in \partial H_b$ . Moreover,  $\partial H_a$  and  $\partial H_b$  are both connected. It follows that  $c$  separates  $a$  from  $b$  in  $\partial H$  as required.

**Lemma 3.2 :** *Suppose  $p, q, r, s \in \partial H$  are distinct and that  $p, q, r, s$  occur in this order along the interval  $\partial H$ . Suppose that  $\alpha, \beta \subseteq H$  are bi-infinite geodesics connecting  $p$  to  $r$  and  $q$  to  $s$  respectively. Then  $\alpha \cap \beta \neq \emptyset$ .*

**Proof :** Simple planar topology shows that  $\alpha$  bounds a half-plane,  $H_\alpha \subseteq H$ . This is convex and hence intrinsically Gromov hyperbolic. We have  $\partial H_\alpha \subseteq \partial H$  and  $\text{end}(H_\alpha) = \{p, r\}$ . In other words,  $\partial H_\alpha$  is the subinterval of  $\partial H$  with endpoints  $p$  and  $r$ . Similarly,  $\beta$  bounds a convex half-space,  $H_\beta$ , with  $\partial H_\beta \subseteq \partial H$  and  $\text{end}(H_\beta) = \{q, s\}$ . Note that neither  $\partial H_\alpha$  nor  $\partial H_\beta$  is contained in the other.

Suppose, for contradiction, that  $\alpha \cap \beta = \emptyset$ . Now neither  $H_\alpha$  nor  $H_\beta$  is contained in the other, and so  $H_\alpha \cap H_\beta = \emptyset$ . But since  $\text{end}(H_\alpha) \cap \text{end}(H_\beta) = \emptyset$ , it follows easily that  $\partial H_\alpha \cap \partial H_\beta = \emptyset$ , giving a contradiction.  $\diamond$

Before discussing how we apply this, we give some general definitions that will be used again later.

Suppose  $(X, \rho)$  and  $(Y, d)$  are metric spaces, and let  $\psi : X \rightarrow Y$  be any map (not necessarily continuous). Let  $F : [0, \infty) \rightarrow [0, \infty)$  be an increasing function.

**Definition :** We say that  $\psi$  is *F-proper* if for all  $x, y \in X$ ,  $\rho(x, y) \leq F(d(\psi(x), \psi(y)))$ . We say that  $\psi$  is *coarsely proper* if it is *F-proper* for some function  $F$ . (This is sometimes termed “uniformly proper” in the literature.) We say that  $\psi$  is *quasi-isometric* if it is *F-proper* of some linear function  $F$ .

The function  $F$  is referred to as the *parameter* of properness or quasi-isometry.

Given any subset  $A \subseteq \mathbf{H}^3$ , we define its *limit set* as the intersection of  $\partial \mathbf{H}^3$  with the closure of  $A$  in  $\mathbf{H}^3 \cup \partial \mathbf{H}^3$ .

**Lemma 3.3 :** Suppose that  $H$  is a complete path-metric space homeomorphic to a half-plane. Suppose that  $\psi : H \rightarrow \mathbf{H}^2$  is a quasi-isometric map. The limit set of  $\psi(H)$  is a  $K$ -quasi-arc, where  $K$  depends only on the parameters of  $\psi$ .

For our applications, we can assume that  $\psi$  is continuous, and that  $\psi$  restricted to  $\text{fr}(H)$  extends to a continuous map of the closed interval. This will eliminate a few technical details.

**Proof :** By the quasi-isometric invariance of hyperbolicity, we see that  $H$  is intrinsically hyperbolic, and  $\psi$  extends to a continuous map of  $H \cup \partial H$  to  $\mathbf{H}^3 \cup \partial \mathbf{H}^3$ . The restriction of  $\psi$  to  $\partial H$  is a homeomorphism from  $\partial H$  to the limit set,  $\gamma$ , of  $\psi(H)$ . Thus, by Lemma 3.1,  $\gamma$  is a closed interval.

Now consider points,  $x, y, z, w \in \gamma$ , occurring in this order. These are, respectively, the  $\psi$ -images of points  $p, q, r, s \in \partial H$ . Let  $\alpha$  and  $\beta$  be bi-infinite geodesics in  $H$  connecting  $p$  to  $r$  and  $q$  to  $s$ . By Lemma 3.2,  $\alpha \cap \beta \neq \emptyset$ . But  $\psi(\alpha)$  is quasigeodesic in  $\mathbf{H}^3$ , and hence remains a bounded distance from the hyperbolic geodesic  $[x, z]$ . Similarly,  $\psi(\beta)$  remains a bounded distance from  $[y, w]$ . It follows that  $d([x, z], [y, w])$  is bounded in terms of the parameters of  $\psi$ . Thus  $\gamma$  is a quasi-arc as claimed.  $\diamond$

#### 4. Simply degenerate ends.

Let  $\Gamma$  be a singly degenerate surface group with quotient  $M = \mathbf{H}^3/\Gamma$ . Write  $Y \subseteq \mathbf{H}^3$  for the hyperbolic convex hull of  $\Lambda\Gamma$ , and write  $\text{core}(M) = Y/\Gamma \subseteq M$  for the convex core of  $M$ . We suppose that  $\text{inj}(M) > 0$ . (This is sometimes termed “bounded geometry”.)

In this case, Minsky [Min1,Min2], shows that  $Y$  is equivariantly quasi-isometric to a certain “singular Sol” model space having a natural singular foliation. (The dependence of the parameters on  $\text{inj}(M)$  and  $\text{genus}(\Sigma)$  is not addressed there, but could, in principle be extracted from the approach discussed in [Bow1,Bow2].) Miyachi [Miy] shows that leaves in this foliation give rise to quasi-isometrically embedded planes. However, his argument does not give uniformity of quasi-arcs. Here we describe another approach, which does give uniformity, and also bypasses much of the difficult part of [Min1,Min2] (namely relating the geometry of  $\text{core}(M)$  to Teichmüller geodesics, and hence to singular Sol geometry).

Throughout the rest of this paper, we describe a constant or function as “uniform” if it ultimately depends only on the initial data, namely  $\text{genus}(\Sigma)$  and  $\text{inj}(M)$ . (It is for this reason that we have substituted the term “coarsely proper” for the more usual “uniformly proper”.)

Now by simple degeneracy and interpolation of pleated surfaces [Bon,T], we can find a sequence of hyperbolic (i.e. constant curvature  $-1$ ) metrics,  $\rho_i$ , on  $\Sigma$  and uniformly lipschitz homotopy equivalences,  $f_i : \Sigma_i \rightarrow \text{core}(M)$ , where  $\Sigma_i = (\Sigma, \rho_i)$ . The diameters of the images  $f_i(\Sigma_i)$  are necessarily bounded, and we can assume, moreover, that each  $f_i(\Sigma_i)$  separates  $f_{i-1}(\Sigma_{i-1})$  from  $f_{i+1}(\Sigma_{i+1})$  and that for all  $i > 0$ ,  $d(f_i(\Sigma_i), f_{i+1}(\Sigma_{i+1}))$  is bounded above and below by uniform positive constants. We may as well take the lower bound to be 1. We can also take  $f_0$  to be an isometry from  $\Sigma_0$  to the boundary

of  $\text{core}(M)$ . One can show that  $\bigcup_{i=0}^{\infty} f_i(\Sigma_i)$  is uniformly quasidense in  $\text{core}(M)$ , i.e. each point of  $\text{core}(M)$  lies within a bounded distance of some  $f_i(\Sigma_i)$ .

Lifting to  $\mathbf{H}^3$ , we obtain a sequence of equivariant uniformly lipschitz maps,  $\phi_i : X_i \rightarrow \mathbf{H}^3$ , where  $X_i \cong \mathbf{H}^2$  is the universal cover of  $\Sigma_i$ . Moreover, it is shown in [Min1] that the maps  $\phi_i$  are uniformly coarsely proper. Indeed, the parameters are computable in terms of  $\text{genus}(\Sigma)$  and  $\text{inj}(M)$  (see [Bow1]).

A simple consequence of this, in turn, is that if we choose  $r > 0$  sufficiently large, then the relation,  $\sim_r$ , defined on  $X_i \times X_{i+1}$  by  $x \sim_r y$  if  $d(\phi_i(x), \phi_i(y)) \leq r$  is a uniform (depending on  $r$ ) quasi-isometry from  $X_i$  to  $X_{i+1}$ . By the stability of quasigeodesics, it follows that if  $x \sim_r x'$  and  $y \sim_r y'$  then  $\phi_i([x, y]_i)$  is a bounded Hausdorff distance from  $\phi_{i+1}([x', y']_{i+1})$ , where  $[x, y]_i$  denotes the geodesic in  $X_i$  from  $x$  to  $y$ . Indeed, there is some uniform  $s > 0$  such that the relation  $\sim_s$  restricted to  $[x, y]_i \times [x', y']_{i+1}$  is a uniform quasi-isometry from  $[x, y]_i$  to  $[x', y']_{i+1}$ .

Suppose that  $x, y, z \in X_i$ . We define  $\text{cent}_i(x, y, z) \in X_i$  to be the nearest point to  $z$  in  $[x, y]_i$ . Another consequence of the above remarks is that if  $x, y, z \in X_i$  and  $x', y', z' \in X_{i+1}$  with  $x \sim_r x'$ ,  $y \sim_r y'$  and  $z \sim_r z'$ , then  $d(\phi_i(\text{cent}_i(x, y, z)), \phi_{i+1}(\text{cent}_{i+1}(x', y', z')))$  is uniformly bounded in terms of  $r$ .

## 5. Proof of the main theorem.

In this section, we prove Theorem 2.1 by constructing quasi-isometric maps of half-planes into  $\mathbf{H}^3$ . We begin with a couple of technical observations.

By a *riemannian rectangle* we shall mean a riemannian metric  $\rho$  on the square  $[0, 1]^2$ , which is isometric to a euclidean metric in a neighbourhood of the “horizontal sides”  $[0, 1] \times \{0\}$  and  $[0, 1] \times \{1\}$ . We refer to the intervals  $\{t\} \times [0, 1]$  as “vertical”.

Suppose that  $J$  and  $J'$  are compact real intervals (or path metric spaces homeomorphic, and hence isometric, to compact intervals). Suppose that  $\sim \subseteq J \times J'$  is a quasi-isometry. We note:

**Lemma 5.1 :** *We can identify  $J$  and  $J'$  with the horizontal sides of a riemannian rectangle,  $R$ , so that each vertical interval has bounded length, so that the inclusions of  $J$  and  $J'$  into  $R$  are quasi-isometries, and so that the inclusion of  $J$  into  $R$  composed with the quasi-isometry  $\sim$  agrees up to bounded distance with inclusion of  $J'$  into  $R$ .*

This can be deduced using the fact that a quasi-isometry of intervals agrees up to bounded distance with a diffeomorphism.

Now suppose that  $J$  and  $J'$  are real intervals, and that  $\phi : J \rightarrow \mathbf{H}^3$  and  $\phi' : J' \rightarrow \mathbf{H}^3$  are coarsely proper lipschitz maps. Let  $\sim \subseteq J \times J'$  be the relation defined by  $x \sim y$  if  $d(\phi(x), \phi'(y)) \leq r$  for some fixed  $r$ . Suppose that  $\sim$  is a quasi-isometry. (For example, if  $\text{HausDist}(\phi(J), \phi'(J')) \leq r$  where  $\text{HausDist}$  denotes Hausdorff distance.) Let  $R$  be a riemannian rectangle as given by Lemma 5.1. We can extend  $\phi \sqcup \phi'$  to a map  $\psi : R \rightarrow \mathbf{H}^3$  by mapping each vertical interval linearly to a geodesic segment in  $\mathbf{H}^3$ . The resulting map  $\psi$  will be uniformly coarsely proper. It will also be uniformly coarsely lipschitz, in the

sense that  $d(\phi(x), \phi(y))$  is bounded above by a uniform linear function of  $\rho(x, y)$ . (Indeed by constructing the metric on  $R$  sensibly, one can assume it to be uniformly lipschitz.)

We shall apply this construction in the situation where we have a sequence of intervals,  $(J_i)_{i \in \mathbb{N}}$  and uniformly proper maps  $\phi_i : J_i \rightarrow \mathbf{H}^3$ , with  $\text{HausDist}(\phi_i(J_i), \phi_{i+1}(J_{i+1}))$  bounded. The above construction gives us riemannian rectangles,  $R_i$ , between  $J_i$  and  $J_{i+1}$  and maps  $\psi_i : R_i \rightarrow \mathbf{H}^3$  that are uniformly coarsely lipschitz and coarsely proper. Gluing these together, we get a riemannian half-space,  $H = \bigcup_{i=0}^{\infty} R_i$ , and a coarsely lipschitz map  $\psi : H \rightarrow \mathbf{H}^3$ . In the case of interest which we describe below,  $\psi$  will be quasi-isometric.

We now return to the set-up described in Section 4, where we have a sequence of planes,  $X_i \cong \mathbf{H}^2$ , and uniformly coarsely proper lipschitz maps  $\phi_i : X_i \rightarrow \mathbf{H}^3$ . It is notationally convenient to assemble the  $X_i$  into a disjoint union  $\Xi = \bigsqcup_{i=0}^{\infty} X_i$ . We refer to  $\Xi$  as a “stack” of “sheets”  $X_i$ . We write  $\phi = \bigcup_i \phi_i$  for the map  $\phi : \Xi \rightarrow \mathbf{H}^3$ . Thus  $\phi(\Xi)$  is quasidense in the convex hull,  $Y$ , of the limit set  $D = \Lambda\Gamma$ .

By an  $r$ -chain, for  $r \geq 0$ , we mean a sequence  $\underline{x} = (x_i)_{i \in \mathbb{N}}$ , with  $x_i \in X_i$  and  $d(\phi_i(x_i), \phi_{i+1}(x_{i+1})) \leq r$  for all  $i$ . From the separation properties of the images  $\phi_i(X_i)$ , we see that  $(\phi_i(x_i))_i$  is a quasigeodesic sequence in  $Y$ , and hence converges on some point, denoted  $\pi(\underline{x})$ , in  $D$ .

It is not hard to see that one can find some uniform  $r_0 \geq 0$  such that each point of  $\text{cut}(D)$  has the form  $\pi(\underline{x})$  for some  $r_0$ -chain. (In particular, it follows that  $\text{cut}(D)$  consists entirely on non-conical limit points, as observed in the introduction.) For details, see [Bow2].

Suppose  $a, b \in \text{cut}(D)$  are distinct. We can find  $r_0$ -chains,  $\underline{a}$  and  $\underline{b}$  such that  $a = \pi(\underline{a})$  and  $b = \pi(\underline{b})$ . Let  $J_i = [a_i, b_i]_i$  and write  $\phi_i : J_i \rightarrow \mathbf{H}^3$  for the restriction of  $\phi_i$  to  $J_i$ . As observed in Section 4,  $\text{HausDist}(\phi_i(J_i), \phi_{i+1}(J_{i+1}))$  is uniformly bounded. Thus, we can embed the  $J_i$  in a riemannian half-plane,  $H$ , and construct a map  $\psi : H \rightarrow \mathbf{H}^3$  as above. From the construction,  $\psi(H) \subseteq Y$ . We denote the metric on  $H$  by  $\rho$ .

**Lemma 5.2 :** *The map  $\psi : H \rightarrow \mathbf{H}^3$  is uniformly quasi-isometric.*

**Proof :** We already know that  $\psi$  is uniformly coarsely lipschitz. Thus, given  $x, y \in H$ , we want to show that  $d(x, y)$  is bounded above by a uniform linear function of  $d(\psi(x), \psi(y))$ . The argument follows that in [Mit].

Since  $\bigcup_i J_i$  is uniformly quasidense in  $H$ , we can assume that  $x, y \in \bigcup_i J_i$ . Let  $p = \psi(x) = \phi(x)$  and  $q = \psi(y) = \phi(y)$ . Let  $\alpha = [p, q] \subseteq Y$  be the geodesic segment in  $Y \subseteq \mathbf{H}^3$  connecting  $p$  to  $q$ . Let  $p_0 = p, p_1, \dots, p_n = q \in \alpha$  cut  $\alpha$  into  $n \leq d(p, q) + 1$  segments, each of length at most 1.

Now  $\phi(\Xi)$  is quasidense in  $Y$ , so we can find points  $x_i \in \Xi$  with  $d(p_i, \phi(x_i))$  uniformly bounded. We can take  $x_0 = x$  and  $x_n = y$ . We write  $x_i \in X_{j(i)}$ . Since  $d(\phi_j(X_j), \phi_{j+1}(X_{j+1})) \geq 1$  for all  $j$ , we can choose the  $x_i$  so that  $|j(i+1) - j(i)| \leq 1$  for all  $i$ .

Now, let  $z_i = \text{cent}_{j(i)}(a_i, b_i, x_i) \in J_{j(i)}$ . Note that  $z_0 = x_0 = x$  and  $z_n = x_n = y$ . Now,  $d(\phi(a_{j(i)}), \phi(a_{j(i+1)})) \leq r_0$ ,  $d(\phi(b_{j(i)}), \phi(b_{j(i+1)})) \leq r_0$ , and by construction,  $d(\phi(x_i), \phi(x_{i+1}))$  is uniformly bounded. Thus, as observed at the end of Section 5,  $d(\phi(z_i), \phi(z_{i+1}))$  is uniformly bounded. By construction,  $\phi(z_i) = \psi(z_i)$  and  $\phi(z_{i+1}) = \psi(z_{i+1})$ . Since

$|j(i+1) - j(i)| \leq 1$ ,  $z_i$  and  $z_{i+1}$  lie in the same rectangle,  $R_j$ , of  $H$ . Now  $\psi$  restricted to  $R_j$  is uniformly proper. Thus,  $\rho(z_i, z_{i+1})$  is bounded above by a uniform constant,  $k$ , say. Thus,  $\rho(x, y) = \rho(z_0, z_n) \leq kn \leq k(d(p, q) + 1) = k(d(\psi(x), \psi(y)) + 1)$  as required.  $\diamond$

Now, by Lemma 3.3, the limit set,  $\gamma$ , of  $\psi(H)$  is a uniform quasi-arc with endpoints  $a$  and  $b$ . Since  $\psi(H) \subseteq Y$ , we see that  $\gamma \subseteq D$ .

We have shown that any pair of points of  $\text{cut}(D)$  are connected by a uniform quasi-arc in  $D$ . It follows that  $D$  is a uniform quasidendrite, thus proving Theorem 2.1.

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